

Incremental Encoders

Standard Stainless steel, hollow shaft, optical

5826 (Hollow shaft)

Push-Pull / RS422



Thanks to their stainless-steel housing, the incremental hollow shaft encoders type 5826 are particularly suitable for those applications that make high demands on the composition and properties of the materials used.

Stainless steel encoders are therefore often used in areas subjected to aggressive cleaning materials, as a result of high hygiene requirements.















High rotational Temperature High protection speed range level

field Short pr

Optical senso

Custom-fit

- · With cable connection
- . Through hollow shaft with 10 mm or 12 mm diameter
- · Protection up to IP66

Adaptable

- High resolution up to 5000 ppr
- Numerous connection possibilities, thanks to wide range of interfaces and supply voltages

Order code Hollow shaft

8.5826

. 1 X X 1



a Flange

1 = with spring element short

b Hollow shaft

 $6 = \emptyset 10 \text{ mm} [0.39"]$

 $8 = \emptyset 12 \text{ mm } [0.47'']$

- Output circuit / Power supply
- 1 = RS422 (with inverted signal) / 5 V DC
- 7 = RS422 (with inverted signal) / 5 ... 30 V DC 4 = RS422 (with inverted signal) / 10 ... 30 V DC
- 5 = Push-Pull (without inverted signal) / 5 ... 30 V DC
- 2 = Push-Pull (without inverted signal) / 10 ... 30 V DC
- 6 = Push-Pull (with inverted signal) / 5 ... 30 V DC
- 3 = Push-Pull (with inverted signal) / 10 ... 30 V DC
- d Type of connection
- 1 = radial cable, 1 m [3.28'] PVC cable

Pulse rate

25, 50, 60, 100, 125, 200, 250, 256, 300, 360, 500, 512, 600, 720, 800, 1000, 1024, 1200, 1250, 1500, 2000, 2048, 2500, 3000, 3600, 4000, 4096, 5000

(e.g. 100 pulses => 0100) Other pulse rates on request



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Technical data

Mechanical characteristics					
Speed	max. 6000 min ^{-1 1)}				
Moment of intertia	approx. 6.0 x 10 ⁻⁶ kgm ²				
Starting torque – at 20°C [68°F]	< 0.05 Nm				
Weight	approx. 0.4 kg [14.11 oz]				
Protection acc. to EN 60529	IP66				
Working temperature range without seal	-20°C +80°C [-4°F +176°F]				
Material shaft	stainless steel				
Shock resistance acc. EN 60068-2-27	2000 m/s ² , 6 ms				
Vibration resistance acc. EN 60068-2-6	100 m/s ² , 10 2000 Hz				

Electrical characteristi	cs					
Output circuit	RS422 (TTL-compatible)	Push-Pull				
Power supply	5 V DC (±5 %) or 10 30 V DC	10 30 V DC				
Power consumption (no load	d)					
without inverted signal	_	typ. 55 mA / max. 125 mA				
with inverted signal	typ. 40 mA / max. 90 mA	typ. 80 mA / max. 150 mA				
Permissible load / channel	max. ±20 mA	max. ±30 mA				
Pulse frequency	max. 300 kHz	max. 300 kHz				
Signal level HIGH	min. 2.5 V	min. +V - 2.5 V				
LOW	min. 0.5 V	max. 2.0 V				
Rising edge time t _r	max. 200 ns	max. 1 μs				
Falling edge time t _f	max. 200 ns	max. 1 μs				
Short circuit proof						
outputs ²⁾	yes 3)	yes				
Reverse polarity protection						
of the power supply	no; 10 30 V DC: yes	yes				
UL approval	File 224618					
CE compliant acc. to	EMC guideline 2004/108/EC					
RoHS compliant acc. to	guideline 2002/95/EC					

Terminal assignment

Output circuit	Type of connection	Cable (isolate unused wires individually before initial start-up)											
1, 2, 3, 4, 5, 6, 7	1	Signal:	0 V	+V	0 Vsens ⁴⁾	+Vsens ⁴⁾	Α	Ā	В	B	0	0	Ť
		Cable colour:	WH 0.5 mm ²	BN 0.5 mm ²	WH	BN	GN	YE	GY	PK	BU	RD	shield

Using RS422 outputs and long cable distances, a wave impedance has to be applied at each cable end.

+V: Encoder power supply +V DC

0 V: Encoder power supply ground GND (0 V)

0 V_{sens} / + V_{sens} : Using the sensor outputs of the encoder, the voltage

present can be measured and if necessary increased

accordingly.

A, \overline{A} : Incremental output channel A Β, B: Incremental output channel B

0, $\overline{0}$: Reference signal

PH ±: Plug connector housing (Shield)

Dimensions

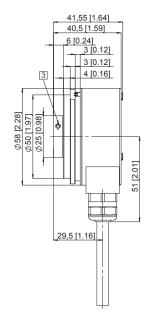
Flange with spring element short Flange type 1

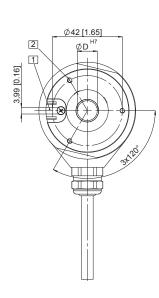
1 Torque stop slot,

Recommendation: Cylindrical pin DIN 7, ø 4 [0.16]

2 3 x M3, 5 [0.2] deep

 $\begin{tabular}{ll} \hline \end{tabular}$ Recommended torque for the clamping ring 1.0 Nm





¹⁾ For continuous operation 3000 min-1, ventilated

²⁾ If supply voltage correctly applied3) Only one channel allowed to be shorted-out: At +V = 5 V DC short circuit to channel, 0 V, or +V is permitted. At +V = 10 ... 30 V DC short circuit to channel or 0 V is permitted.

The sensor cables are connected to the supply voltage internally.
If long feeder cables are involved they can be used to adjust or control the voltage at the encoder.